### Evaluating the Energy Efficiency of Few-Shot Learning for Object Detection in Industrial Settings

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### Outline

- Motivation
- Methodology
- Experimental Results
- Conclusion

#### Motivation

### **Motivation**<sup>[1/2]</sup> - **Introduction**

#### **AI in Industrial Applications**

- Sustainability and energy efficiency are critical requirements in industrial settings
- Data can be scarce or expensive to acquire due to privacy regulations
- Hardware and bandwidth resources are limited on edge devices

#### **Few-shot Learning**

- Learning from a limited amount of data
- Reduced resource demands, alleviation of lengthy model training
- Finetuning-based approaches have shown promising results

#### **Current Limitations**

• Quantifying and enhancing the energy efficiency of finetuning-based FSL models is an underexplored topic

### **Motivation**<sup>[2/2]</sup> - **Contributions**

- Explore the trade-off between the training performance and energy efficiency of finetuningbased methods for few-shot object detection
- Propose Efficiency Factor as a novel metric to quantify the performance vs energy consumption trade-off of FSL models
- Perform a thorough performance and energy consumption evaluation of finetuning-based object detectors on three benchmarks of volatile industrial data



## Methodology<sup>[1/3]</sup> - Problem Formulation

- Base dataset D<sup>train</sup>
  - Contemporary object detection modules are typically pretrained in a large dataset containing abundant annotated images (e.g., MS-COCO)
  - This dataset contains images of objects belonging to  $N_B$  classes
  - Under this problem formulation this dataset constitutes the base dataset *D*<sup>train</sup> that the Yolo model is initially trained on.
- Novel few-shot task
  - Most object detection datasets with industrial data are typically small
  - Under this problem formulation, these datasets constitute our novel few-shot tasks
  - Each *novel few-shot task (dataset with new classes)* contains  $N_N$  classes that the model has not encountered before
  - Each novel few-shot task can be broken down as follows:
  - Support set S: Used for training, contains 1-30 samples / class (also called *samples*)
  - Query set Q: Used for evaluation
- Objective:
  - Develop a model that can be adapted to each novel few-shot task (e.g., learn to identify new classes) and achieve good performance in it.



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**Object Detector Model:** YOLOv8n (3.2M parameters)

Main Components:

- Backbone feature extractor
  - CSPDarknet53 based on the Feature Pyramid Network (FPN) architecture
- Detection Head
  - Convolutional layers
  - Three detection modules for multi-scaled object detection



Source: https://github.com/ultralytics/ultralytics/issues/189

#### **Backbone**

- Primary Function:
  - Acts as the feature extractor in the neural network.
- Process Details:
  - Processes input images through convolutional layers.
  - Generates feature maps capturing essential visual details.
- Impact on Performance:
  - Influences the speed of object detection.



https://github.com/ultralytics/ultralytics/issues/189

Source:

#### **Detection Head**

- Primary Function:
  - Responsible for making final predictions in the network.
- Process Details:
  - Receives processed feature maps from the backbone.
  - Applies convolutional layers specifically designed to predict class probabilities, object locations, and size.
- Outputs:
  - Generates bounding boxes around detected objects.
  - Assigns class labels and confidence scores to each detection.



#### **Detection Module**

- **Primary Function:** 
  - Localizes and classifies objects within the image.
- **Process Details:** 
  - Integrates feature maps from both the backbone • and neck.
  - Utilizes multiple scales for detection to enhance ٠ accuracy at various object sizes.
- **Components:** 
  - Consists of multiple detection layers tailored for different scales.
  - Each layer predicts bounding boxes, class • probabilities, and objectness scores.



Source:

### Methodology<sup>[3/3]</sup> - Proposed Approach

1<sup>st</sup> stage: Pretrain model in the base dataset  $D^{train}$  (MS-COCO as the base dataset)

2<sup>nd</sup> stage: Finetune different modules of the model in the novel few-shot dataset (PPE, CS, Fire) *to enable the model recognize the new classes* 

#### **Finetuning strategies:**

We employ three strategies for finetuning:

- Whole model (full finetuning), finetuned parameters: 3.2M
- Detection Heads (partial finetuning), finetuned parameters: 1.7M
- Detection Modules (partial finetuning), finetuned parameters: 750K

These strategies train different parts of the Yolov8 model to investigate the best optimization technique under Few-shot learning.



Strategy 1: Whole Mode



### **Experimental Results**

### **Results**<sup>[1/5]</sup> - **Datasets**

Utilization of 3 open-source datasets of objects found in industrial settings

Dataset	No. Classes	Classes	Purpose
PPE Dataset	4	Helmet, Gloves, Mask, Cloth	Localize and identify PPE for first responders
Construction Safety (CS) Dataset	3	Helmets, Vests, other PPE	Identify presence/absence of PPE in industrial settings
Fire Dataset	1	Fire scenes	Locate and recognize fires



PPE Dataset

CS Dataset

Fire Dataset

### **Results**<sup>[2/5]</sup> - **Evaluation Metrics**

• **Object Detection Performance:** Mean Average Precision (mAP)

$$mAP = \frac{1}{N} \sum_{i=1}^{N} AP_i$$

- Energy Efficiency: Energy consumption (Wh) during finetuning stage
- Efficiency Factor (EF): Novel metric that takes into consideration both mAP and energy consumption (EC)

$$EF = \frac{mAP}{1 + EC}$$

• Higher EF values given to models with high mAP during evaluation and low energy consumption during finetuning

### **Results**<sup>[3/5]</sup> - Model Performance

#### Main Insights:

- Increasing the number of shots (*images per class*) leads to increased model performance
- Comparable performance for all finetuning strategies in most cases for the same number of shots



• Notably, the Full model achieves worst results than the Detector/Head because the whole model needs bigger dataset to train efficiently.

### **Results**<sup>[4/5]</sup> - **Energy Efficiency**

#### Main Insights:

- Reducing the number of finetuned parameters leads to reduced energy consumption
- Trade-off between model performance and energy efficiency
- Finetuning only the detection heads achieves the best performance vs efficiency balance



- Finetuning the detector modules is the most energy-efficient choice, but the performance (mAP) is poor.
- Finetuning the whole model has the second-best performance, and it is too energy-consuming.
- Finetuning the detection heads leads to the best compromise between performance and energy preservation. 14

### **Results**<sup>[5/5]</sup> - **Performance / Efficiency Trade-off**

#### Main Insights:

- Finetuning less parameters reduces energy consumption but does not necessarily lead to increased EF values
- Best EF values achieved when the number of shots is small



• As the number of shots (*i.e.*, *images per class*) increases, the <u>energy consumption needed to finetune the</u> <u>model outweighs any performance advantage</u> and as a result the EF metric drops significantly.

#### Conclusion

### **Conclusion**<sup>[1/1]</sup>

#### **Takeaway points:**

- Energy efficiency evaluation of FSL approaches has been an underexplored topic
- This study: focus on finetuning-based approaches for object detection in industrial datasets
- Examination of full and partial finetuning approaches on YOLOv8
- Trade-off between model performance and energy efficiency
- Introduction of Efficiency Factor (EF) as a metric that captures and quantifies this trade-off

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### **The TALON Project**

#### **TALON Pillars**

- Al orchestrator for autonomous and dynamic scalability as well as greener AI networks
- Distributed blockchain for high-security, privacy and trust in a heterogeneous application environment
- Flexible E2C deployment for "almost-zero latency" and high-computational capabilities near sensors
- DTs and HIL to boost AI explainability, trustworthiness and transparency

Call: HORIZON-CI 4-2021-HUMAN-01 Topic: HORIZON-CL4-2021-HUMAN-01-01 Type of action: RIA *Total Budget:* € 3.769.382,50 Period: 36 Months



#### **TALON Demonstrators**



#### UC #1: Automatic UATV coordination

Efficiently improve trajectory planning and energy/data optimization in UATV coordination using TALON's AI-Orchestrator.



#### UC #2: I5.0 automation & planning

Streamline development in TALON's I5.0 pilot with CI/CD, automation tools, and data management workflow automation.

#### UC #3: AR/VR for training and maintenance

Implement TALON's AR/VR training pilot with evaluation methodology, CI/CD integration, and AI orchestration in metallurgy plant.



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#### UC #4: Human-Robot Collaboration

TALON's human-robot collaboration pilot focuses on AI analytics for production optimization and real-time AR/VR feedback integration.

production optimization and real-time AR/VR feedback integration. ]TALON's human-robot collaboration pilot focuses on AI analytics for

Human-Kobot Collaboration

### **MetaMind Innovations**

# **Minds**



MINDS is the first spin-off technology company of the University of Western Macedonia. The company specializes in advancing the Internet of Things (IoT) with Artificial Intelligence (AI) and Virtual Reality (VR) technologies, offering smart solutions for critical infrastructure. It was founded in 2021 by Professor Panagiotis Sarigiannidis and a team of academics and researchers, with a focus on the development of leading, reliable and customized technological solutions that enhance business efficiency, security and innovation.

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